

7. (Amended) The method according to [one of the preceding claims] claim 1, wherein a graph comparison function is used, which comprises a jet comparison function that takes into account the similarity of the jets corresponding to one another.

10. (Amended) The method according to [one of the claims 7 to 9] claim 7, wherein the jet comparison function is defined as a function of single jet comparison functions of jets corresponding to one another.

12. (Amended) The method according to claim 10 [or 11], wherein sub-jets of the corresponding jets are taken into account for determining a single jet comparison, and wherein a single jet comparison function is defined as a function of sub-jet comparison functions.

14. (Amended) The method according to [one of the claims 7 to 13] claim 7, wherein different node-dependent jet comparison functions and/or single jet comparison functions and/or sub-jet comparison functions are used.

15. (Amended) The method according to [one of the claims 7 to 9] claim 7, in combination with claim 2, wherein the bunch jets of the reference bunch graph  $B^M$  are divided into sub-bunch jets  $b_k^M$ , and the jet comparison function between the sub-bunch jets  $b_k^M$  of the reference bunch graph and the corresponding sub-jets  $j'_n$  of the image graph  $G'$  for  $n$  nodes for  $m$  recursions is calculated according to the following formulae:

$$S_{jet}(B^M, G') = \sum_n \omega_n S_n(B_n^M, J_n'), \text{ or}$$

$$S_{jet}(B^M, G') = \prod_n (S_n(B_n^M, J_n'))^{\omega_n}, \text{ wherein}$$

$\omega_n$  is a weighting factor for the  $n$ -th node  $n$ , and the comparison function  $S_n(B_n^M, J_n')$  for the  $n$ -th node of the reference bunch graph with the  $n$ -th node of the image graph is given by:

$S(B^M, j')$  =  $\Omega\left(\left\{S_{kl}(b_k^M, j_l')\right\}\right)$  =:  $\Omega(M)$ , with

$\Omega^{(0)}(M) = \sum_i \omega_i \Omega_i^{(1)}(M_i^{(1)})$ , or

$\Omega^{(0)}(M) = \prod_i \left(\Omega_i^{(1)}(M_i^{(1)})\right)^{\omega_i}$ , or

$\Omega^{(0)}(M) = \max_i \left\{ \omega_i \Omega_i^{(1)}(M_i^{(1)}) \right\}$ , or

$\Omega^{(0)}(M) = \min_i \left\{ \omega_i \Omega_i^{(1)}(M_i^{(1)}) \right\}$ , wherein  $\bigcup_i M_i^{(1)} = M$

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$\Omega_i^{(m-1)}(M_i^{(m-1)}) = \sum_j \omega_j \Omega_j^{(m)}(M_j^{(m)})$ , or

$\Omega_i^{(m-1)}(M_i^{(1)}) = \prod_j \left(\Omega_j^{(m)}(M_j^{(m)})\right)^{\omega_j}$ , or

$\Omega_i^{(m-1)}(M_i^{(m-1)}) = \max_j \left\{ \omega_j \Omega_j^{(m)}(M_j^{(m)}) \right\}$ , or

$\Omega_i^{(m-1)}(M_i^{(m-1)}) = \min_j \left\{ \omega_j \Omega_j^{(m)}(M_j^{(m)}) \right\}$ , wherein  $\bigcup_j M_j^{(m)} = M_i^{(m-1)}$  and with

$S(b^M, j') = \sum_n \omega_n S_n(j_n^M, j')$ , or

$S(b^M, j') = \prod_n (S_n(j_n^M, j'))^{\omega_n}$ , or

$S(b^M, j') = \max_n \left\{ \omega_n S_n(j_n^M, j') \right\}$ , or

$S(b^M, j') = \min_n \left\{ \omega_n S_n(j_n^M, j') \right\}$ .

18. (Amended) The method according to [one of the preceding claims] claim 1, wherein, after the recognition of each structure, a step for determining the significance of the recognition is provided.

21. (Amended) The method according to [one of the preceding claims] claim 1, wherein, in addition, each structure is associated with the reference images corresponding to the reference graphs and/or the reference graphs from the reference bunch graphs for which the values of the graph comparison functions lie within a predetermined range.

22. (Amended) The method according to [one of the preceding claims] claim 1, wherein the colour information comprises hue values and/or colour saturation values and/or intensity values determined from the reference image data and the image data, respectively.

23. (Amended) The method according to [one of the claims 1 to 22] claim 1, wherein the step of providing the reference graphs and the reference bunch graphs, respectively, comprises fetching the reference graphs and the reference bunch graphs from a central and/or decentralized data base.

24. (Amended) The method according to [one of the preceding claims] claim 23, wherein a regular grid is used as a net-like structure of the reference graph, the nodes and links of said regular grid defining rectangular meshes.

25. (Amended) The method according to [one of the claims 1 to 23] claim 1, wherein an irregular grid is used as a net-like structure of the reference graph, the nodes and links of said irregular grid being adapted to the structure to be recognized.

27. (Amended) The method according to [one of the preceding claims] claim 1, wherein Gabor filter functions and/or Mallat filter functions are used as class of filter functions for convolution with the reference image data and image data, respectively.